Assignment \#2 Solutions
Problem 2: We verify that $Q(A)$ is a probability by checking the three conditions.

- Since $P(\emptyset)=0$, we conclude

$$
Q(\emptyset)=P(\emptyset \mid B)=\frac{P(\emptyset \cap B)}{P(B)}=\frac{P(\emptyset)}{P(B)}=0
$$

since $\{\emptyset \cap B\}=\emptyset$. Similarly,

$$
Q(\Omega)=P(\Omega \mid B)=\frac{P(\Omega \cap B)}{P(B)}=\frac{P(B)}{P(B)}=1
$$

since $\{\Omega \cap B\}=B$.

- We observe that $A^{c} \cup A=\Omega$ so that

$$
B=B \cap \Omega=\left(A^{c} \cup A\right) \cap B=\left(A^{c} \cap B\right) \cup(A \cap B) .
$$

Since $\left(A^{c} \cap B\right)$ and $(A \cap B)$ are disjoint, we conclude that

$$
P(B)=P\left(\left(A^{c} \cap B\right) \cup(A \cap B)\right)=P\left(A^{c} \cap B\right)+P(A \cap B) .
$$

Dividing both sides by $P(B)$ gives

$$
\frac{P(B)}{P(B)}=\frac{P\left(A^{c} \cap B\right)}{P(B)}+\frac{P(A \cap B)}{P(B)} .
$$

In other words, $1=Q\left(A^{c}\right)+Q(A)$, or $Q\left(A^{c}\right)=1-Q(A)$, as required.

- If $A_{1}, A_{2}, \ldots$ are disjoint, then since $\left(A_{1} \cup A_{2} \cup \cdots\right) \cap B=\left(A_{1} \cap B\right) \cup\left(A_{2} \cap B\right) \cup \cdots$ with $\left(A_{i} \cap B\right) \cap\left(A_{j} \cap B\right)=\emptyset$ for $i \neq j$, we conclude that

$$
P\left(\left(A_{1} \cup A_{2} \cup \cdots\right) \cap B\right)=P\left(\left(A_{1} \cap B\right) \cup\left(A_{2} \cap B\right) \cup \cdots\right)=P\left(A_{1} \cap B\right)+P\left(A_{2} \cap B\right)+\cdots
$$

and so

$$
\begin{aligned}
Q\left(A_{1} \cup A_{2} \cup \cdots\right)=\frac{P\left(\left(A_{1} \cup A_{2} \cup \cdots\right) \cap B\right)}{P(B)} & =\frac{P\left(A_{1} \cap B\right)+P\left(A_{2} \cap B\right)+\cdots}{P(B)} \\
& =\frac{P\left(A_{1} \cap B\right)}{P(B)}+\frac{P\left(A_{2} \cap B\right)}{P(B)}+\cdots \\
& =Q\left(A_{1}\right)+Q\left(A_{2}\right)+\cdots
\end{aligned}
$$

Problem 3 (Exercise 1.2): This exercise was discussed in class; we just complete the missing details. Since $f_{X, Y}(x, y)=1 / \pi$ for $x^{2}+y^{2} \leq 1$, we have

$$
\mathbb{E}(X Y)=\iint_{x^{2}+y^{2} \leq 1} x y \cdot \frac{1}{\pi} \cdot d x d y
$$

To compute this double integral, we use polar coordinates: $x=r \cos \theta, y=r \sin \theta, 0 \leq r \leq 1$, $0 \leq \theta<2 \pi, d x d y=r d r d \theta$, and so

$$
\begin{aligned}
\mathbb{E}(X Y)=\iint_{x^{2}+y^{2} \leq 1} x y \cdot \frac{1}{\pi} \cdot d x d y & =\int_{0}^{2 \pi} \int_{0}^{1} r \cos \theta \cdot r \sin \theta \cdot \frac{1}{\pi} \cdot r d r d \theta \\
& =\int_{0}^{2 \pi} \int_{0}^{1} \frac{r^{3}}{\pi} \cos \theta \sin \theta d r d \theta \\
& =\frac{1}{4 \pi} \int_{0}^{2 \pi} \cos \theta \sin \theta d \theta \\
& =\frac{1}{8 \pi} \int_{0}^{2 \pi} \sin (2 \theta) d \theta \\
& =\left.\frac{1}{16 \pi} \cos (2 \theta)\right|_{0} ^{2 \pi} \\
& =0
\end{aligned}
$$

Furthermore, we find

$$
\mathbb{E}(X)=\int_{-1}^{1} x \cdot \frac{2}{\pi} \sqrt{1-x^{2}} d x \quad \text { and } \quad \mathbb{E}(Y)=\int_{-1}^{1} y \cdot \frac{2}{\pi} \sqrt{1-y^{2}} d y
$$

Therefore, since both of these integrals are the same, we only need to evaluate one of them. Thus, letting $u=1-x^{2}$ so that $d u=-2 x d x$, we find

$$
\mathbb{E}(Y)=\mathbb{E}(X)=\int_{-1}^{1} x \cdot \frac{2}{\pi} \sqrt{1-x^{2}} d x=-\frac{1}{\pi} \int_{0}^{0} \sqrt{u} d u=0
$$

Hence, we conclude that $\operatorname{cov}(X, Y)=\mathbb{E}(X Y)-(\mathbb{E} X)(\mathbb{E} Y)=0$ and so $X$ and $Y$ are, in fact, dependent but uncorrelated random variables.

Problem 4 (Exercise 1.3): If $(X, Y)$ is uniformly distributed on the square with corners $( \pm 1, \pm 1)$, then the joint density of $(X, Y)$ is given by

$$
f_{X, Y}(x, y)= \begin{cases}\frac{1}{4}, & \text { if }-1 \leq x \leq 1,-1 \leq y \leq 1 \\ 0, & \text { otherwise }\end{cases}
$$

- The marginal density of $X$ is given by

$$
f_{X}(x)=\int_{-\infty}^{\infty} f_{X, Y}(x, y) d y
$$

If $-1 \leq x \leq 1$, then the range of possible $y$ values is $-1 \leq y \leq 1$, and so

$$
f_{X}(x)=\int_{-1}^{1} \frac{1}{4} d y=\frac{1}{2}
$$

That is,

$$
f_{X}(x)= \begin{cases}\frac{1}{2}, & \text { if }-1 \leq x \leq 1 \\ 0, & \text { otherwise }\end{cases}
$$

Similarly, if $-1 \leq y \leq 1$, then the range of possible $x$ values is $-1 \leq x \leq 1$, and so

$$
f_{Y}(y)=\int_{-\infty}^{\infty} f_{X, Y}(x, y) d x=\int_{-1}^{1} \frac{1}{4} d x=\frac{1}{2}
$$

That is,

$$
f_{Y}(y)= \begin{cases}\frac{1}{2}, & \text { if }-1 \leq y \leq 1 \\ 0, & \text { otherwise }\end{cases}
$$

Since $f_{X, Y}(x, y)=f_{X}(x) \cdot f_{Y}(y)$, we conclude that $X$ and $Y$ are independent.

- If $X$ and $Y$ are independent, then they are necessarily uncorrelated since $E(X Y)=E(X) E(Y)$ so that

$$
\operatorname{cov}(X, Y)=E(X Y)-E(X) E(Y)=0
$$

Problem 5 (Exercise 1.1): Since the volume of the unit sphere in $\mathbb{R}^{3}$ is $4 \pi / 3$, the joint density of $(X, Y, Z)$ is

$$
f_{X, Y, Z}(x, y, z)= \begin{cases}\frac{3}{4 \pi}, & \text { if } x^{2}+y^{2}+z^{2} \leq 1 \\ 0, & \text { otherwise }\end{cases}
$$

- Therefore, the marginal density of $(X, Y)$ is given by

$$
f_{X, Y}(x, y)=\int_{-\infty}^{\infty} f_{X, Y, Z}(x, y, z) d z
$$

If $x, y, z$ are constrained to have $x^{2}+y^{2}+z^{2} \leq 1$, then for fixed $x$ with $-1 \leq x \leq 1$, the range of possible $y$ values is $-\sqrt{1-x^{2}} \leq y \leq \sqrt{1-x^{2}}$, and that the range of $z$ is $-\sqrt{1-x-y^{2}} \leq z \leq \sqrt{1-x^{2}-y^{2}}$. It therefore follows that

$$
f_{X, Y}(x, y)=\int_{-\sqrt{1-x-y^{2}}}^{\sqrt{1-x^{2}-y^{2}}} \frac{3}{4 \pi} d z=\frac{3}{2 \pi} \sqrt{1-x^{2}-y^{2}}
$$

for $-1 \leq x \leq 1$ and $-\sqrt{1-x^{2}} \leq y \leq \sqrt{1-x^{2}}$. In other words,

$$
f_{X, Y}(x, y)= \begin{cases}\frac{3}{2 \pi} \sqrt{1-x^{2}-y^{2}}, & \text { if } x^{2}+y^{2} \leq 1 \\ 0, & \text { otherwise }\end{cases}
$$

- The marginal density of $X$ is then given by

$$
f_{X}(x)=\int_{-\infty}^{\infty} f_{X, Y}(x, y) d y=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X, Y, Z}(x, y, z) d z d y
$$

From our work above, we find that if $-1 \leq x \leq 1$, then

$$
f_{X}(x)=\int_{-\sqrt{1-x^{2}}}^{\sqrt{1-x^{2}}} \frac{3}{2 \pi} \sqrt{1-x^{2}-y^{2}} d y
$$

This can be solved with a $u$-substitution. Let $y=\left(\sqrt{1-x^{2}}\right) \cdot \sin u$ so that

$$
d y=\left(\sqrt{1-x^{2}}\right) \cdot \cos u d u
$$

and so

$$
\begin{aligned}
\int_{-\sqrt{1-x^{2}}}^{\sqrt{1-x^{2}}} \frac{3}{2 \pi} \sqrt{1-x^{2}-y^{2}} d y & =\frac{3}{2 \pi}\left(1-x^{2}\right) \int_{\sin ^{-1}(-1)}^{\sin ^{-1}(1)}\left(\sqrt{1-\sin ^{2} u}\right) \cdot \cos u d u \\
& =\frac{3}{2 \pi}\left(1-x^{2}\right) \int_{-\pi / 2}^{\pi / 2} \cos ^{2} u d u
\end{aligned}
$$

being careful to watch our new limits of integration and remembering that $\sin ^{-1}(-1)=-\pi / 2$ and $\sin ^{-1}(1)=\pi / 2$. Recalling the half-angle identities for cosine, we find

$$
\int \cos ^{2} u d u=\int \frac{1}{2}+\frac{1}{2} \cos (2 u) d u=\frac{u}{2}+\frac{1}{4} \sin (2 u)
$$

and so

$$
\begin{aligned}
\frac{3}{2 \pi}\left(1-x^{2}\right) \int_{-\pi / 2}^{\pi / 2} \cos ^{2} u d u & =\frac{3}{2 \pi}\left(1-x^{2}\right)\left[\frac{u}{2}+\frac{1}{4} \sin (2 u)\right]_{-\pi / 2}^{\pi / 2} \\
& =\frac{3}{2 \pi}\left(1-x^{2}\right)\left[\frac{\pi / 2}{2}-\frac{-\pi / 2}{2}\right] \\
& =\frac{3}{4}\left(1-x^{2}\right)
\end{aligned}
$$

In summary,

$$
f_{X}(x)= \begin{cases}\frac{3}{4}\left(1-x^{2}\right), & \text { if }-1 \leq x \leq 1 \\ 0, & \text { otherwise }\end{cases}
$$

Note: You can check that $f_{X}$ is, in fact, a density by verifying that

$$
\int_{-1}^{1} \frac{3}{4}\left(1-x^{2}\right) d x=1
$$

Problem 6: Since $X_{1}, X_{2}, X_{3}$ are independent and identically distributed, by can immediately conclude by symmetry that the 6 events

$$
\begin{aligned}
& \left\{X_{1}<X_{2}<X_{3}\right\},\left\{X_{1}<X_{3}<X_{2}\right\},\left\{X_{2}<X_{1}<X_{3}\right\}, \\
& \left\{X_{2}<X_{3}<X_{1}\right\},\left\{X_{3}<X_{1}<X_{2}\right\},\left\{X_{3}<X_{2}<X_{1}\right\}
\end{aligned}
$$

are equally likely. Since $X_{1}, X_{2}, X_{3}$ are continuous random variables, we know that events such as $\left\{X_{1}=X_{2}\right\}$ have probability zero. Thus, we conclude that these six events are exhaustive; that is,

$$
\begin{aligned}
& P\left\{X_{1}<X_{2}<X_{3}\right\}=P\left\{X_{1}<X_{3}<X_{2}\right\}=P\left\{X_{2}<X_{1}<X_{3}\right\} \\
& \quad=P\left\{X_{2}<X_{3}<X_{1}\right\}=P\left\{X_{3}<X_{1}<X_{2}\right\}=P\left\{X_{3}<X_{2}<X_{1}\right\} \\
& \quad=\frac{1}{6} .
\end{aligned}
$$

It now follows that
(a) $P\left\{X_{1}>X_{2}\right\}=P\left\{X_{2}<X_{1}<X_{3}\right\}+P\left\{X_{2}<X_{3}<X_{1}\right\}+P\left\{X_{3}<X_{2}<X_{1}\right\}=\frac{1}{2}$,
(b) $P\left\{X_{1}>X_{2} \mid X_{1}>X_{3}\right\}=P\left\{X_{2}<X_{3}<X_{1}\right\}+P\left\{X_{3}<X_{2}<X_{1}\right\}=\frac{2}{3}$,
(c) $P\left\{X_{1}>X_{2} \mid X_{1}<X_{3}\right\}=P\left\{X_{2}<X_{1}<X_{3}\right\}=\frac{1}{6}$.

